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3	HOUSE PUBLIC SAFETY AND HOMELAND SECURITY COMMITTEE SUBSTITUTE
4	FOR HB160
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9	SYNOPSIS: A bill would authorize the operation of an
10	automated commercial motor vehicle and a commercial
11	motor vehicle with a teleoperation system if the
12	vehicles meet certain criteria.
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14	A BILL
15	TO BE ENTITLED
16	AN ACT
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18	Relating to motor vehicles; to authorize autonomous
19	commercial vehicles operated by an automated driving system
20	and commercial motor vehicles with teleoperation systems.
21	BE IT ENACTED BY THE LEGISLATURE OF ALABAMA:
22	Section 1. For the purposes of this act, the
23	following words shall have the following meanings:
24	(1) AUTOMATED COMMERCIAL MOTOR VEHICLE. A commercial
25	motor vehicle equipped with an automated driving system.
26	(2) AUTOMATED DRIVING SYSTEM. The hardware and
27	software that are collectively capable of performing the

entire dynamic driving task on a sustained basis, regardless
of whether it is limited to a specific operational design
domain.

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- (3) COMMERCIAL MOTOR VEHICLE. A commercial motor vehicle as defined in subdivision (2) of Section 32-9A-1, Code of Alabama 1975.
- (4) CONVENTIONAL DRIVER. A driver who manually exercises in-vehicle braking, accelerating, steering, and transmission gear selection input devices in order to operate a vehicle.
- (5) DYNAMIC DRIVING TASK. All of the real-time operational and tactical functions required to operate a vehicle in on-road traffic excluding strategic functions such as trip scheduling and selection of destinations and waypoints.
- (6) MINIMAL RISK CONDITION. A condition to which a user or an automated driving system may bring a vehicle in order to reduce the risk of a crash when a given trip cannot or should not be completed.
- (7) OPERATIONAL DESIGN DOMAIN. A description of the specific operating domain in which an automated commercial motor vehicle is designed to properly operate, including, but not limited to, roadway types, speed, environmental conditions, and other domain constraints.
- (8) REMOTE DRIVER. A natural person who is not seated in a position to manually exercise braking, accelerating, steering, and transmission gear selection input

devices but is able to perform the entire dynamic driving task.

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- (9) TELEOPERATION SYSTEM. Hardware and software installed on a commercial motor vehicle that allow a remote driver to operate the motor vehicle.
 - Section 2. (a) Unless otherwise provided by this act, an automated commercial motor vehicle and a teleoperation system, including any commercial use or operation of either, are governed exclusively by this act.
 - (b) Notwithstanding any other provision of law, the Department of Transportation is the sole and exclusive state agency with jurisdiction over automated commercial motor vehicles and teleoperation systems that may implement this act.
 - (c) A political subdivision of this state or a state agency may not impose requirements, including taxes or performance standards, related specifically to the operation of a teleoperation system or automated commercial motor vehicle in addition to the requirements of this act.
 - Section 3. Notwithstanding any other provision of law, an automated commercial motor vehicle may operate in this state without a conventional driver physically present in the vehicle if the vehicle meets all of the following criteria:
 - (1) The automated commercial vehicle is capable of operating in compliance with applicable federal law and the traffic and motor vehicle laws of this state.

1 (2) The automated commercial vehicle is registered 2 and titled in accordance with the laws of this state.

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- (3) The automated commercial vehicle is certified in accordance with 49 C.F.R. Part 567 as being in compliance with federal motor vehicle safety standards and bears the required certification label or labels, including reference to any exemption granted under applicable federal law.
- (4) The automated commercial vehicle can achieve a minimal risk condition if a failure occurs rendering the vehicle unable to perform the dynamic driving task relevant to its intended operational design domain or if the vehicle exits its operational design domain.
- (5) The automated commercial vehicle is covered by motor vehicle liability coverage in an amount not less than two million dollars (\$2,000,000).
- (6) The registration of an automated commercial motor vehicle shall not be interpreted to abrogate or amend any statutory or regulatory provisions or any aspects of common law pertaining to liability for any harm or injury caused.
- Section 4. (a) The owner of an automated commercial vehicle, or the lessee if the vehicle is leased or rented, is considered the operator of the vehicle for the purpose of assessing compliance with applicable traffic or motor vehicle laws, including the rules of the road.
- (b) The automated driving system is considered to be licensed to operate the vehicle.

Section 5. When an accident occurs involving an automated commercial motor vehicle, the requirements of Chapter 10, Title 32, Code of Alabama 1975, shall be deemed satisfied if the vehicle remains on the scene of the accident and the vehicle, owner, a person on behalf of the owner, or operator promptly contacts appropriate law enforcement entities and communicates the information required by Chapter 10, Title 32, Code of Alabama 1975.

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Section 6. (a) Notwithstanding any other provision of this act, a commercial motor vehicle equipped with a teleoperation system may operate without a conventional driver physically present in the vehicle if a remote driver is operating the vehicle.

- (b) When a remote driver is operating a commercial motor vehicle, the remote driver is considered to be the operator of the vehicle for the purpose of assessing compliance with applicable traffic or motor vehicle laws, including the rules of the road.
- (c) The remote driver shall hold the proper class of license required for a conventional driver to operate the vehicle.
- (d) When an accident occurs involving a commercial motor vehicle equipped with a teleoperation system, the requirements of Chapter 10, Title 32, Code of Alabama 1975, shall be deemed satisfied if the vehicle remains on the scene of the accident and the owner or remote driver promptly contacts appropriate law enforcement entities and communicates

the information required by Chapter 10, Title 32, Code of Alabama 1975.

- Section 7. A commercial motor vehicle equipped with a teleoperation system registered in this state shall meet all of the following requirements:
 - (1) The motor vehicle shall be in compliance with applicable federal law.
 - (2) The motor vehicle shall be certified in accordance with federal regulations in 49 C.F.R. Part 567 as being in compliance with applicable federal motor vehicle safety standards and shall bear the required certification label or labels, including reference to any exemption granted under applicable federal law.
 - (3) The motor vehicle shall be capable of being operated in compliance with the applicable traffic and motor vehicle laws of this state, regardless of whether the vehicle is operated by a remote driver.
 - (4) The motor vehicle shall be covered by motor vehicle liability coverage in an amount of not less than two million dollars (\$2,000,000).
 - (5) The motor vehicle shall be able to achieve a reasonably safe state, such as bringing the vehicle to a stop, if a failure of the teleoperation system occurs that renders the remote driver unable to perform the entire dynamic driving task for the vehicle.
 - Section 8. This act is supplemental and shall not be construed to repeal, modify, or preempt any liability that may

be incurred under existing common or statutory law applicable
to a vehicle owner, operator, manufacturer, component part
supplier, or retailer.

Section 9. This act shall become effective
immediately following its passage and approval by the
Governor, or its otherwise becoming law.